

modely

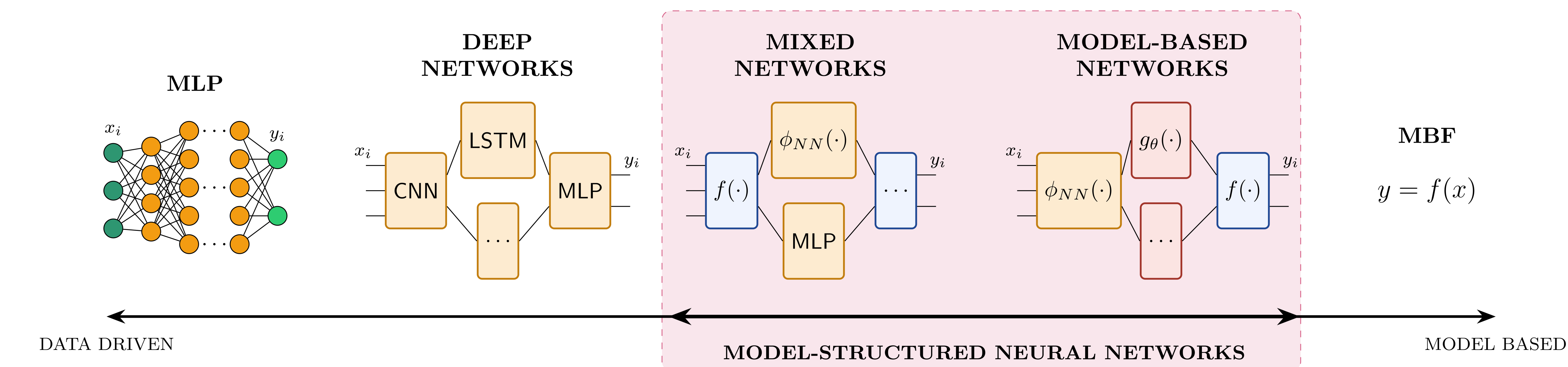
neuralize your model



Gastone Pietro Rosati Papini, Alice Plebe, Mojtaba Sharifzadeh, Mattia Piazza, Sebastiano Taddei, Giovanni Scialla, Francesco Baroni, Davide De Martini, Giovanni Maria Francesco La Scala, Gioele Defrancesco, Filippo Faccini



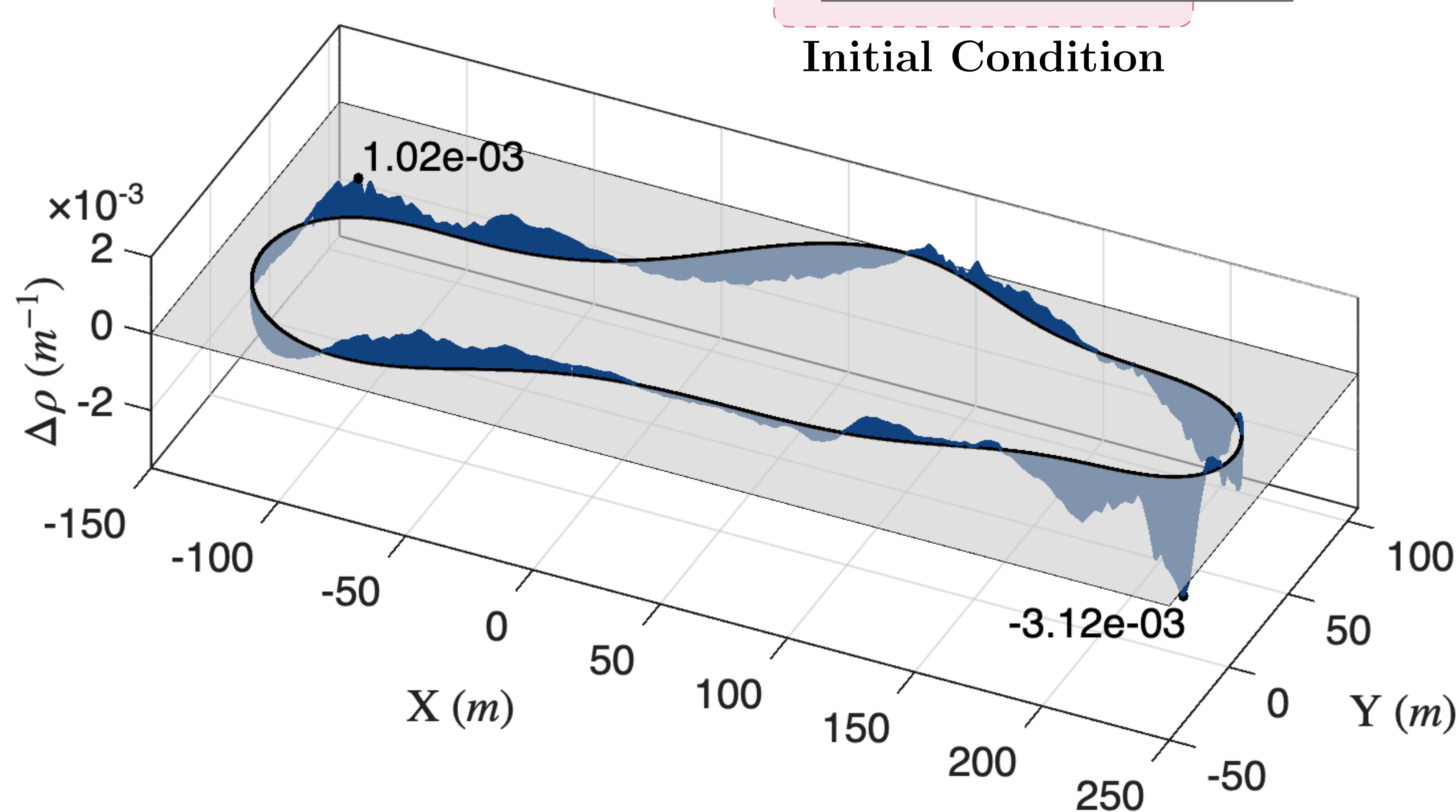
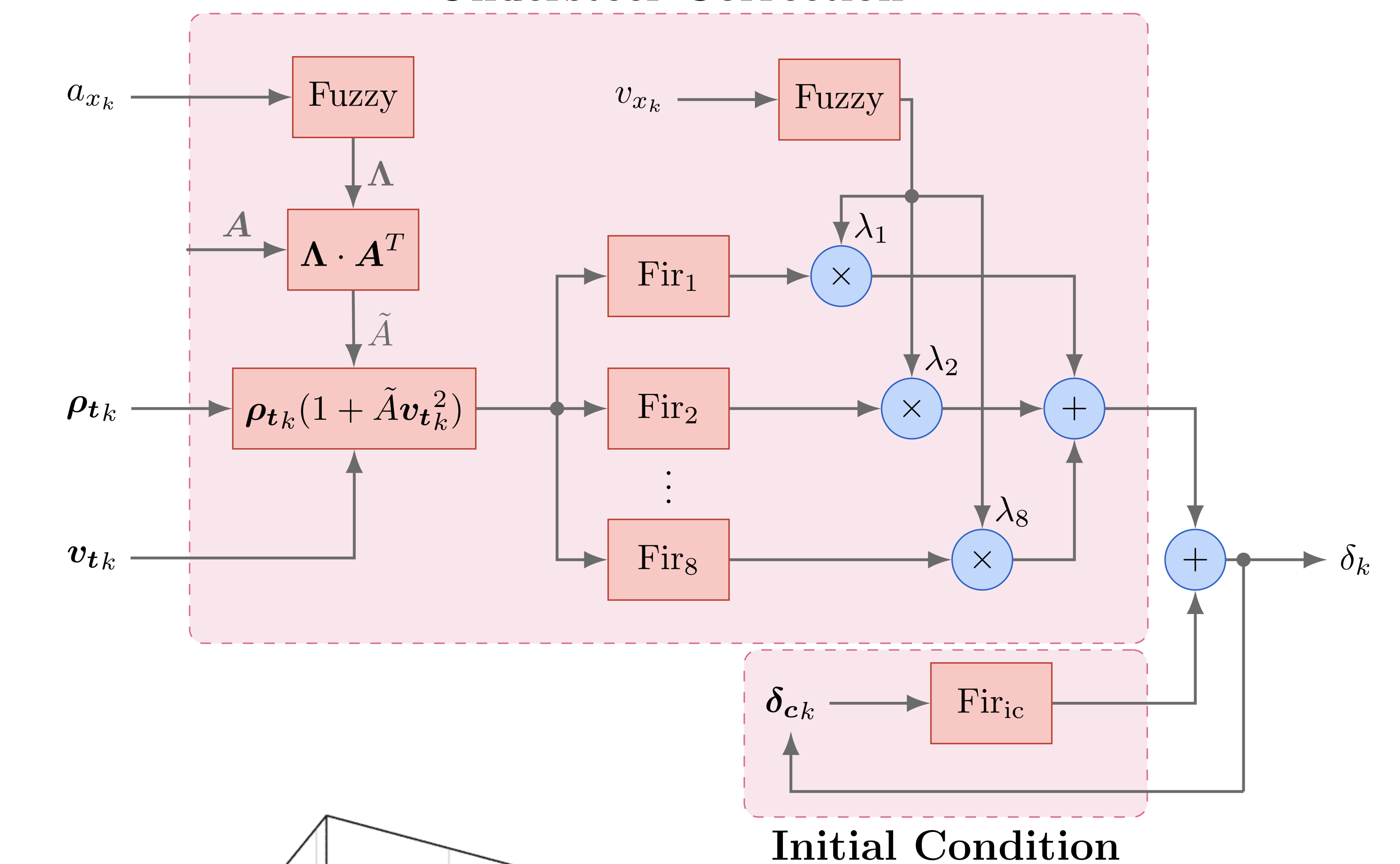
MODEL WITH MODEL-STRUCTURED NEURAL NETWORKS



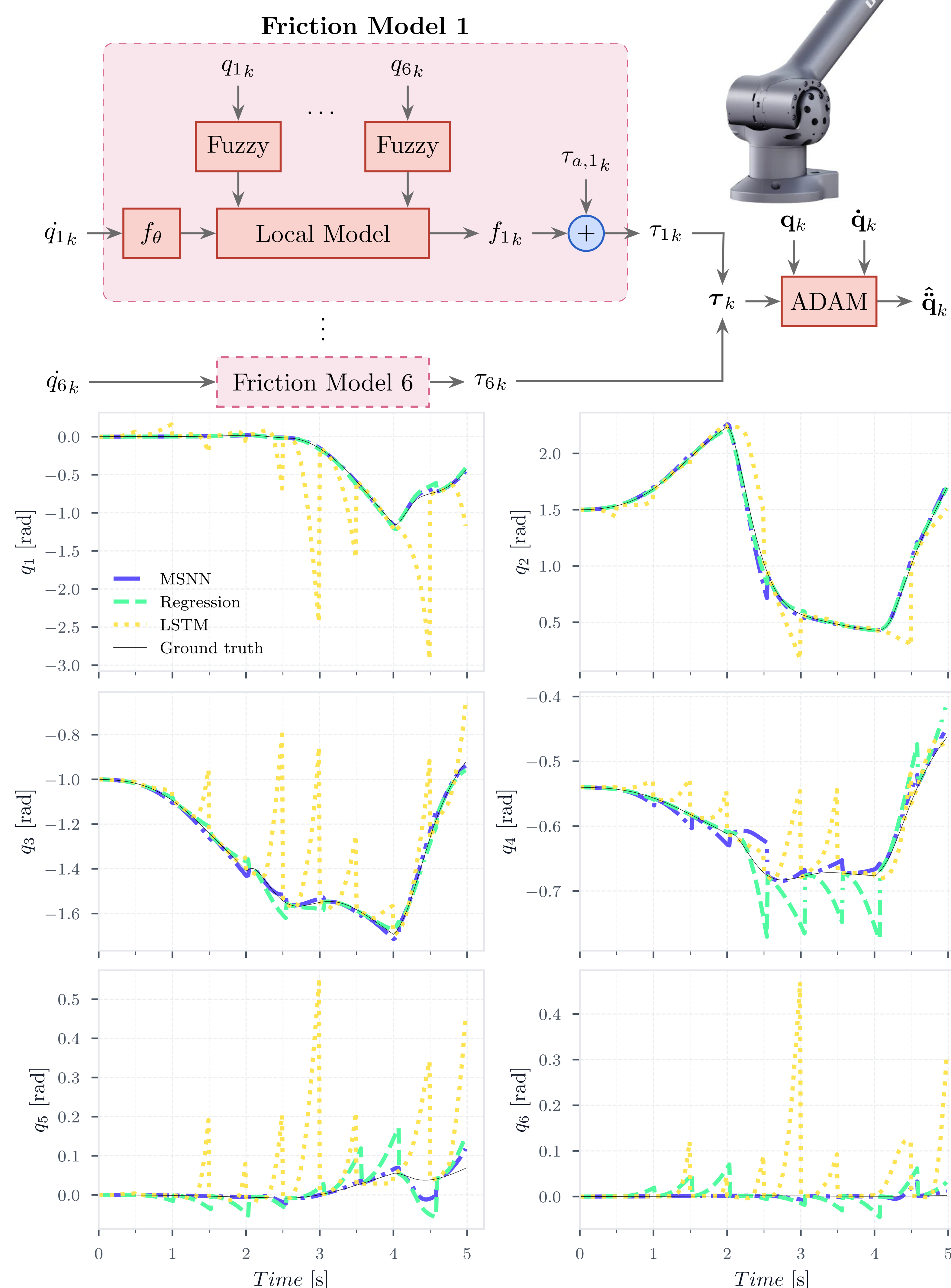
VEHICLE LATERAL CONTROL



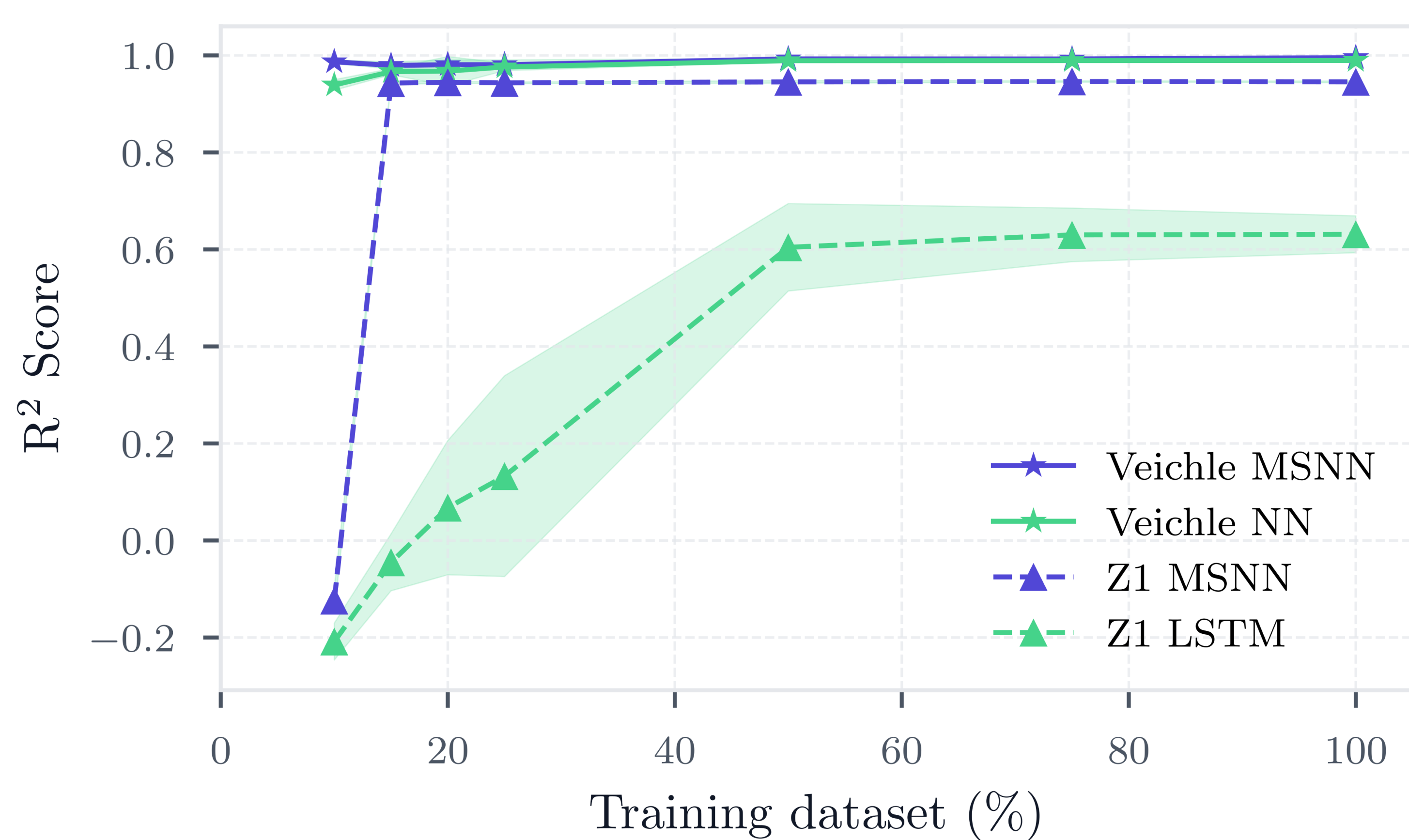
Understeer Correction



MANIPULATOR FRICTION ESTIMATION



KEY FEATURES



- **Model-oriented** neural architectures
- Flexible and **interpretable** modeling
- **Data-efficient** and robust learning
- Differentiable **end-to-end** system design